Gesturing Through Cursors:
Implementing Multiple Pointers in Group Support Systems

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Abstract

The focus of this paper is on the issues underlying the concept of gesturing. Gesturing from one human to another appears to span all cultural boundaries; one could possibly call it a universal means of communication. Studies of group work have shown that gesturing makes up over 35% of all interactions. Participants gestured to enact ideas, to signal turn-taking, to focus the attention of the group, and to refer objects on the work surface. Specifically, this paper explores gesturing as applied to users of Group Support Systems. The definition of gesturing is extended beyond simple telepointers to include 1) the use of motion as a means of expression, and 2) movement that expresses or emphasizes an idea, a sentiment or attitude. We address such issues as: at what level of interaction should gesturing be supported, how large and what shape should gesture pointers be, how should they move, what are network and processor throughput requirements, and what effect group size may have. Our results show that full motion computer gesturing can be supported on PC-LAN systems for small groups. Gesturing for medium and large groups requires the use of special techniques such as regulating transmission rates, motion smoothing, and point & quiver cursors. These techniques can also be applied to wide area network implementations to reduce network traffic and latency problems.

1. Introduction

Group Support Systems an an emerging area of research that spans computer-supported cooperative work (CSCW) and group decision support systems (GDSS). CSCW is defined as “the study and theory of how people work together, and how the computer and related technologies affect group behavior” [10]. CSCW implementors build “computer-based systems that support two or more users engaged in a common task (or goal) and that provide an interface to a shared environment” [7]. These systems usually facilitate communication between members of a small group and provide task-specific tools. The software rarely regulates the actual meeting process; the designers expect that normal social protocols between participants will suffice.

On the other hand, a GDSS is “an interactive computer-based system that facilitates the solution of unstructured problems by a set of decision-makers working together as a group” [4]. The design goal is to increase the efficiency and effectiveness of meetings. The usual method is to “manage” the interactions between the group members by enforcing rules of meeting protocol and structure [21]. Existing GDSS tools facilitate both small (3-6 members) and large (7-30) groups through the various stages of the decision-making process [3, 33].

We believe that meetings in most corporate situations lie somewhere in between CSCW and GDSS; not all meetings result in decisions nor do all group processes center around a task. Sometimes structured processes are crucial at meetings; at others they are debilitating. Rather than split semantic hairs about where our research resides, we will use the label Group Support Systems (GSS). This research entails understanding how groups interact; applying that understanding to designing systems that help people work together; and observing people using our systems. The last point often constrains our implementations to standard delivery platforms (such as IBM PCs), and much of our effort is devoted to overcoming the platform limitations. The focus of this paper is on gesturing: why it is required, how it can be implemented on a computer, and what pragmatic decisions must be made during implementation.

2. Gesture

gesture: 1) the use of motions of the body as a means of expression, 2) a movement of the body that expresses or emphasizes an idea, a sentiment or attitude [16].

Some sort of gesturing takes place throughout any interaction between human beings. Gesturing appears to span all cultural boundaries; one could possibly call it a universal means of communication. Gesturing not only occurs between people, but also between people and their artifacts. In an ethnographic study of eight short-term, small-group design sessions, Tang built a descriptive framework that categorized activities over a shared work surface (large sheets of paper tacked on a table or white board) [28, 29]. Three primitive actions were observed, and were combined to mediate several essential functions.

• Action:
  - listing produces non-spatially located text or alphanumeric notes;
drawing produces graphical objects, typically a 2-
dimensional sketch with spatially located textual an-
otations;

• gesturing is a purposeful body movement that com-
municates specific information, e.g. pointing to an
existing drawing.

• Function:
  
• storing information refers to preserving group infor-
mation in some form for later recall;
• expressing ideas involves interactively creating rep-
resentations of ideas in some tangible form;
• mediating interaction facilitates the collaboration of
the group and includes turn-taking and focusing at-
tention.

Hand gestures played a prominent role in all work sur-
face activities (about 35% of all actions). Participants ges-
tured to enact ideas, to signal turn-taking, to focus the
attention of the group, and to reference objects on the work
surface [28, 29].

Clearly, gesturing is of paramount importance in group
interaction. Tang demonstrated this for small design
groups, and it is our belief that gesturing is essential for
almost all group activities involving a shared work sur-
face. We are exploring hand gesturing over displays in
Group Support Systems. Obviously, as soon as group work
is moved from a "manual" face-to-face environment to a
dispersed "computer-supported" environment, many ques-
tions arise about gesturing. How can hand gestures be
tracked as input? How do we display a gesture on a screen?
If there is to be a gesture icon, how large must it be? How
should it move? What happens as group size increases
(scalability)? What network bandwidth is needed? We
will address these questions in Section 4, after first review-
ing existing implementations of gesturing in Section 3. Our
experiences implementing different gesturing strategies via
multiple pointers on a LAN-supported IBM PC platform
are described in Section 5, which is heavily illustrated by
performance benchmarks.

3. Previous Research

We are concerned with enhancing a group’s real-time in-
teraction when using groupware tools in a computerized
shared visual work surface, where one’s actions are imme-
diately visible to all [7]. The displays are software equiva-
lents to white boards and flip charts; the tools could be text
editors, hypertext, structured drawing tools, and so on.

Many collaborative systems do not support gesturing.
For example, we now see teleconferencing setups that com-
bine voice conferencing with facsimile transmission, elec-
tronic white boards, and even slow scan video. While all
participants can see the same resulting information, ges-
tures referring to an artifact are only visible through indi-
rection or not at all. For example, if one points at a drawing
on a document at one site, a person at the other site must find
their equivalent document and determine where the refer-
ence is. Similarly, one rarely sees the fine-grained process
of others creating and manipulating artifacts. While peo-
ple can get their job done without gesturing, we argue that
much of the conversation is used as a substitute to ges-
turing, e.g. “I’m pointing to the second line in the third
paragraph”, and that breakdowns are frequent, e.g. “which
one do you mean?”.

One of the first systems to support gesturing explicitly
was BoardNoter, a computerized white board used to sup-
port face to face meetings [27]. Gesturing was through a
single large “telepointer”. One person at a time could grab
and control this special cursor, which was then seen on ev-
ey display. All other individual cursors remained invisible
to the group. In addition to tracking the cursor, clicking
the mouse button would cause a static image of the pointer
to be deposited (and remain) on the board [26]. Several com-
mercial view-sharing systems, which allow people to share
standard single-user application through serial interaction
[9], can also support single cursors. Unlike BoardNoter,
there is no difference between the local cursor and tele-
pointer, e.g. Farallon’s Timbuktu [8]. The common cursor
responds to each user’s mouse movement. When several
people move their mice, the result is “cursor wars”.

The first serious works in gesturing, all motivated by
Tang’s work (described above), were implemented using
two different technologies: video fusion, and computa-
tional space. VideoDraw was the original video-based sys-
tem [30]. Each person has a monitor that displays the
image of a camera pointing to the other person’s monitor.
Participants draw directly onto the monitor, and the camera
captures both the other person’s hand and the drawing un-
derneath. Feedback is eliminated through polarizing filters.
The result is that the shared workspace contains (from one
person’s point of view) his physical hand, pen marks on top
of the screen, plus the other person’s hand and marks in
the image. TeamWorkStation, on the other hand, uses
hardware to fuse video signals [18]. The advantage here
is that people can perform their activity on any work sur-
face (such as a desktop), with a video camera recording
and fusing its image with the work surface image of the
other participant. Finally, VideoWhiteboard allows each
user to see the drawings and a shadow of the gestures of
collaborators at the remote site [31]. Here, people see their
partners and movements as a silhouette appearing on the
other side of a translucent white board. These video sys-
tems are limited. First, participants cannot manipulate each
others marks, since they only see them as a video image.
Second, these systems are not scalable since serious image
deterioration results when too many images are fused.

At the same time, several computational systems were
developed that implemented gestures through multiple cur-
sors. GroupSketch is a computer-based group sketchpad
where one or more people can simultaneously draw, type,
and gesture around the display [11, 13, 12]. Its cursors
were designed specifically for gesturing around the criteria
listed below.

• Since gestures must be seen in order to convey infor-
mation, all cursors within a work surface are always
visible to all participants.

• Cursors must have enough prominence on a multi-
cursor display to attract the attention of other partici-
pants. A large 64x64 bit cursor is used instead of the traditional 16x16 bit cursor.

- Cursors change their shape to reflect a natural action. Four gesture modes are supported (pointing, writing/drawing, erasing, and directing attention) by distinct cursor shapes (a pointing hand, pen, eraser, large arrow respectively).

- Cursors are unique, each identifying the person it belongs to. While face to face gesturing has natural cues to help identify who is gesturing, cursors do not. GroupSketch labels each cursor with its owner’s name and each new cursor is rotated 90 degrees from the last (while the idea of rotation was first put in to reflect different seating orientations of participants around a drawing, its real value was that it allowed up to four cursors to touch the same pixel without overlapping each other).

- Cursor movements appear continuously and with no apparent delay on all displays, which means that they remain synchronized with verbal communication.

- Cursors always maintain their same relative location on every display so that they retain their relation to the work surface objects.

In parallel with GroupSketch came the very similar Commune [2, 19, 20]. Instead of a mouse and a vertical display, Commune users were able to write directly on a flat screen with a pen. This provided them with improved control/display compatibility and fine motor coordination. Many second generation sketching packages now support gesturing, e.g. XGroupSketch [13, 12], a functionally richer window based version of GroupSketch; WScrawl by Brian Wilson [34], GroupScratchPad by Stephen Hayne [14], and ShDr by Paul Dourish [5]. We are also seeing these ideas transferred to the domain of structured drawing: GroupDraw [13, 12], MMM [1] and MUGE [23].

Several computer tools for tasks other than drawing also support gesturing. In ShrEdit, a shared text editor, all insertion “carets” of participants are visible, as well as the text that they type [22]. In rIBIS, a hypertext system supporting argumentation, there are two modes of operation: loosely and tightly coupled. In the latter, a single group cursor available through turn taking is visible to all, thus strengthening the feeling of participation [24]. Both the Multi-User Graphical Editor and the Graphical Issue Analyzer by Pendergast and Hayne [15, 23] have implemented specific gesturing cursors (discussed in the next section).

Finally, several researchers are now investigating “gaze-awareness”, where a person can see where their partner is looking at on the work surface [17]. Although we do not pursue it further in this paper, a person’s gaze is a gesture as well. By tracking another person’s eye movement over the work surface, we see their focus of attention, their degree of interest, obtain cues for topic switching, and so on. The few computational attempts at supporting gaze-awareness rely on overlaying the work surface on top of a video image of a person’s face, and arranging cameras and half-silvered mirrors in such a way that eye references to the work surface are consistent across sites. Again, this video configuration may not be scalable to larger groups.

In summary, existing systems support gesturing through a handful of strategies. These include a single static pointer that is placed on the screen but does not track mouse movement, a single dynamic pointer that follows the mouse, multiple pointers with fine-grained tracking, and video images of actual hands as well as exploring gaze awareness. Of course, there are also systems that do not support gestures at all, but we believe these provide an impoverished work surface for group members [13].

4. A Design Framework for Gesturing

The goal of our research is to focus on a computer-based mechanism for supporting telepresence in the form of gesturing. Telepresence attempts to give meeting participants the feeling that they are all in the same room [6] by sharing the explicit and implicit participant dynamics. Paramount among these actions are gestural and meta-level communications. As we are not targeting a multi-media environment, we have chosen to study the requirements for gesticulation as implemented by multiple cursors that can be displayed on every participant station in real-time.

This section describes some of the design considerations we have encountered in our work on gesturing. It is presented as a loose framework revolving around four aspects: the appearance of a gesture cursor; different ways cursors can express gesturing through motion; the effects of group size and distribution on cursors; and consequences of relaxed “What you see is what I see” (WYSIWIS) [26]. We assume a voice channel is available to the group, and that multiple cursors are preferred over single cursors.

4.1 Cursor appearance

Single cursors are usually presented on a screen as a small (16x16 pixel) bitmap, usually a left-leaning arrow. A naive approach to multiple cursors is to simply copy the appearance of single cursors. However, several issues appear which demand a slightly more sophisticated approach.

Owner identification. Assuming non-anonymous interaction, remote cursors must be easily discernible from the local cursor, and participants should easily be able to distinguish who is doing what. In the first case, color or slight shape changes can be useful. For example, the local cursor might be black (or solid) while the remote cursors are colored (or outlined). In the second, the cursors can be uniquely labeled by a participant’s name so that participants can quickly determine who is doing the gesture. In practice, this may be easy, since user actions are often tied to voice [13]. Although labeling may be left off if some degree of anonymity is desired, participants will likely be able to identify its owner by other clues.

Cursor size. Cursors in most single user graphical user interfaces are quite small. As screens get larger and the display busier, the cursor becomes difficult to find. Most people just jiggle their mouse (we can easily spot motion). Some window systems have tricks for focusing a user on
the cursor location. Examples of the latter are "Xeyes" (two graphical eyes track the cursor), and "oneko" (where a kitten chases the cursor around the screen, eventually to sleep on top of it when idle). When multiple people are using a display, the cursor size becomes much more critical. Since we maintain that cursors are critical to gesturing, a larger size (say 64x64 pixels) would be more appropriate for small group interactions [13, 23]. The tradeoff is that cursors can quickly consume too much screen real estate as group size increases (described later). While we do not yet know what the optimum size is, we caution implementors against choosing the standard 16x16 pixel size just because they are accustomed to it.

Cursor shape. Since many different and natural actions are to be expressed, the cursor shape must change depending on the action—this will add to the quality of the gesture. Both pointing (e.g. finger) and attracting attention (e.g. flashing arrow) have been identified as crucial general actions [11, 13, 23]. If the application requires drawing or listing, the cursor should also reflect this by perhaps using a pencil, a caret, or other shapes that indicates the action. Gratuitous cursor shapes, as implemented in the Aspects groupware system [32] likely have no positive effect.

Cursor lifetime. While it can be useful to have cursors displayed at all times (especially to indicate who is present), inactive cursors can become passively intrusive in larger groups. To address this, remote cursor display can either be put under individual control or can have a decay function over activity and time. Two interesting approaches to decay are to have a gravity function which removes the inactive cursor to a corner of the screen called a parking area, or to have the cursor merely dissolve away [14].

4.2 Gesturing through cursor motion

The presence of a cursor on the screen indicates who is active in the session. It is the motion of the cursor that indicates a pure gesture or a gesture-based activity. We believe that the best gesturing systems will support real time motion on all screens. Unfortunately, some platforms may not allow full motion because of limited network bandwidth, latency, and slow processor speed. The following strategies for supporting low to high bandwidth cursor motions are presented in order of lowest to highest data and processing requirements. The implementation model used is that each workstation sends a message on its cursor' status to the other participants' workstations.

Point. When the user points and presses a mouse button, a single message is sent to all the remote users. The gesturing cursor leaps to the new location from its old one and remains there until its owner sends a new location message. The problem is that a user may not see the sudden transition, thus not noticing the gesture.

Point and quiver. In order to attract the viewers attention, the above strategy is modified so that the receiving station jitters the cursor back and forth in its new position for a period of time.

Limited motion. Only a certain number of gesture messages per second are sent between stations. As the number is increased, the cursor motion moves from being stilted and jerky to a smoother animation. For example, ShDr [5] allows the user to control the number of transmitted cursor movements through a slider in the window's control panel. The fewer messages sent, the less accurately the motion reflects the gesture. Also, the jerky cursor is visually unattractive.

Limited motion with smoothing. After receiving a new cursor position from the sender, the receiving station computes several points in between the previous and the current location, and then animates the cursor through these intermediate points. While this eliminates jerkiness, it still does not guarantee that the path reflects the actual movement of the sender. Note that smoothing can also be applied to Point, and to Point and Quiver. This technique is applicable to slow networks, but does not overcome slow processors.

Full motion. Every time the cursor is locally displayed in a new location, a gesture message is sent. Every movement of the cursor, no matter how small, is immediately broadcast. If the network and processor is fast enough, every receiver will display the cursor exactly as the sender does. For many years the motion picture industry used 16 frames per second as the standard for smooth animation. We feel that between 10-20 msg/sec will support full motion. While sending more messages may be possible, it is probably not necessary.

Which is the best choice? We believe that full motion gesturing is the preferred for most situations. However, there may be special occasions when a user would want to leave a pointer parked at a specific location, such as when long network latency (> .5 seconds) is combined with real-time voice. Full motion may be unacceptable when gestures do not match the verbal communication.

4.3 Group size and distribution

Clearly, cursors convey meta-level communication information, i.e. how many people are in the meeting and how their activity is balanced. As the group size increases, the number of cursors appearing on the screen could begin to intrude on the interaction. One approach to managing this problem is to reduce the size of the remote cursors using a step function. As examples:

1. For one to four people use the "regular" size of 64x64 pixels;
2. For five to six people reduce the cursor size to 32x32;
3. For seven to eight people reduce the size to 16x16, and so on.
4. For larger groups, each user may be displayed as a single pixel on the screen—this will still provide participants with "gestalt" of the activity level.

This step function was implemented in the latest versions of Groupsketch (as illustrated in [12]), MUGE, and GroupscratchPad. Cursor size is altered by the software as people enter and leave the session. This notwithstanding, we feel
that when groups become very large, the lifetime of cursors will need to be adjusted.

Decreasing the size of the cursor severely limits the amount of information it can display. Very small cursors do not have room for a label, so identification becomes problematic. Also, as cursor numbers increase, it will become difficult to tell who is doing something important, and whose voice is tied to which cursor. We believe that the cursor size should be altered to reflect important actions. For example, the cursor size in a medium-sized group of eight people can be quite small (4x4 pixels) [13], but users can press a mouse button and get a large labeled pointing arrow, especially designed to attract the group's attention. Similarly, whenever someone starts to draw or type, their cursor grows to 64x64 pixels. Gesturing can be used to get access to the "floor" or voice channel when individuals are dispersed geographically, particularly useful for sessions using conference calls. Perhaps a "hand-raising" cursor is required?

4.4 Relaxed WYSIWIS

Much of our discussion assumes strict WYSIWIS, where everyone sees exactly the same view. Since we feel that most group software will eventually relax WYSIWIS along congruence of view, transformation of cursor coordinates between the sending and receiving views must be performed. As well, screens have differing resolutions and if a windowing environment is used, windows can be placed on different parts of the screen. This transformation is easily done by mapping the cursor location to a world coordinate system at the sender and 1) if that location is outside the receiver's view discard the message; or 2) map the world coordinate to the receiver's viewport coordinates. It is extremely important that when one user points at a place in their window or screen locally, the same logical place is "gestured" at on the remote stations.

Of course, this leads to a variety of human factors issues. Consider Figure 1, which shows four users actively working on a shared canvas. From user A's perspective, B's view completely overlaps, C partially overlaps, and D is disjoint. First, should A have peripheral awareness of the others in the virtual canvas, particularly those who are completely outside A's viewport (D)? In Shared ARK and MUGE for example, the display includes a miniature of the entire canvas that shows the boundaries of each person's area of view [25, 23]. This conveys some of the meta-level information described earlier. Second, if viewports overlap (A and B), what happens to the gesturing cursors when it moves across a view boundary? For example, if B moves the cursor to the lower right of the screen, would it suddenly disappear from A's view (as in XGroupSketch), or would it "linger" in the last visible spot (as in GIA)? What consequence does this have on gesture interaction? Third, how should views be linked together? Assuming that users will move from a loosely coupled mode where they are working more or less independently to a tightly coupled mode throughout a session (and back), there should be ways to link views and gesture spaces together. For example, MUGE and GIA include the notion of leaders and followers, where users have the option of making their viewports and scrolling actions slaved with one another [23]. A user can be both a leader and a follower; leaders take followers along with them as they move about the work surface (zooming or scrolling).

5. Performance Benchmarks

Successful implementation of full motion gesturing in GSS applications is dependent on the performance characteristics of the network and host operating system. Many of the previous systems have been implemented on UNIX hosts, but we feel that the more realistic corporate environment of IBM PCs and a Graphical User Interface would represent a lowest common denominator. Thus, we conducted our tests in the University of Calgary Norcen Meeting room that has 34 IBM PS/2 Model 55 (386sx/16) PCs networked using both a 16MB Token Ring LAN and a 10MB Ethernet LAN supported by a Novell Netware (V3.21) file server.

Microsoft Windows 3.1\(^1\) applications were used and the communication was managed by the Network Interface Object (NIO) as described by Pendergast and Hayne [23]. The NIO manages application layer communications (OSI) by providing a "channel" object that facilitates the creation of GSS applications by providing virtual, multicast connections that parallel the meeting room metaphor of communications. Multicast connections permit communication between two or more stations using a single network name or address, thus not requiring multiple separate session connections with each one. The NIO implements multicast channels using two transport level protocols: 1) reliable session connections; 2) broadcast datagrams. Depending on the nature of the data, the applications can dynamically select either the reliable (session connection) or unreliable (datagram) path when sending the message. Using the reliable channel requires the NIO to transmit the message to each station individually. Broadcast datagrams are sent just once, independent of the number of stations participating. The unreliable path has limited message size

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\(^1\)Microsoft Windows is a trademark of the Microsoft Corporation
Table 1: Transmission Time in Seconds for 100 Messages

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<thead>
<tr>
<th>Multicast</th>
<th>Datagram</th>
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<td>Revs</td>
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<td>12</td>
<td>25.161</td>
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</table>

Figure 2: Performance Differences between Multicast and Broadcast

as fast as possible and recorded the elapsed time. Using the Novell Netware IPXSPX Windows interface, this time was measured at 2.314 seconds (average), or 23 milliseconds per message (43 messages/second). To measure the overhead of the test program and high level communications handler (NIO), the actual datagram transmission was then disabled and the test repeated. The resulting overhead was approximately 5 milliseconds per message, leaving 18 milliseconds for the actual transmission. This seemed to be slow considering a 16MHz processor and a 16MB Token Ring LAN. This same test was also performed using the 10MB Ethernet protocol. The results from this test were better. It took 14 milliseconds per message, with 5 milliseconds of overhead. However, 9 milliseconds (Ethernet) and 18 milliseconds (Token Ring) still seemed excessive.

To discover if the Windows operating environment had an effect on transmission rates, a DOS test program was created that measured the time required to transmit 100 datagrams (100 bytes each). This program was able to transmit the 100 messages in less than 300 milliseconds (Token Ring) and 100 milliseconds (Ethernet), or about 3 and 1 milliseconds per message respectively (1/6 the time of Windows). Due to the extreme difference between Windows and native DOS, we wanted to pinpoint the problem in Windows by eliminating the Novell interface to the network and substituting the IBM NETBIOS interface. This third test gave results identical to the IPXSPX version. We believe we have verified the existence of a Microsoft Windows' induced delay in the transmission process. One source of the delay comes from having to transfer data packets and command blocks from extended memory to low DOS memory where the adapter can access it. We also suspect that the Windows kernel only processes interrupts after a certain arbitrary number of clock ticks. Reducing the NIO's overhead by 75% would allow transmission of over 50 datagrams/second - far more than we feel is required for gesturing. But, discovering the reason for the delay inside of Windows's kernel and reducing it by just 20% would yield the same results.

5.1 Transmission time

This test determined the time required to transmit messages of various sizes over the unreliable (broadcast datagram) and reliable (multicast) communication channels. The test consisted of a station sending 100 messages as fast as possible and recording the elapsed time. The number of receiving stations was varied from 1 to 12 for message lengths of 100, 1000, and 2000 bytes, thus requiring 1, 2, and 4 network packets respectively. Table 1 presents the elapsed time, in seconds, to transmit 100 messages. Figure 2 illustrates the performance differences between the multicast and broadcast datagram channels.

The transmission times for the datagram channel remained constant while the multicast channel's rate increased linearly with the number of receiving stations. This is as expected since the multicast channel transmits a message to each receiver separately. The amount of time required to transmit (multicast) a 100 byte message to 12 stations is .25 seconds and we predict that for 24 stations it would be .50 seconds. This makes a clear case for the use of unreliable datagram communications for gesture messages even though some datagrams may be lost.

5.2 Datagram throughput

This test was conducted in order to determine the maximum rate that a station could transmit datagram messages of a size appropriate for gestures. A single station (IBM PS/2 55) transmitted 100 datagram messages of 100 bytes (approximately 500 bytes) and is not acknowledged, while the reliable path has no size limits and are guaranteed sent until a time-out occurs.

The NIO is incorporated into several GSS applications, including MUGE, GIA, Graphical Brainstorming [14], and GroupScratchPad [14]. Since all Windows (or DOS) based applications will need to use a network layer (perhaps like the NIO) we felt it necessary to determine if typical LANs and PCs could support gesturing.
from a 20 second run where 4 stations were transmitting (and receiving) at the same time. Station A was not able to transmit at the same rate as the other stations once the send rate was increased to 7 messages per second. Station B began being penalized at 9 or 10 messages a second, while Stations C and D were able to transmit at a high rate for all speeds. At the speeds required for smooth gesturing (minimum of 10-15 per second), Station A was only able to transmit 1 message per second. This results in a very jerky gesture motion. Since a station’s ability to transmit/receive is based on processor speed and location on the ring, certain stations will always be at a disadvantage. This indicates that the software controlling the gesturing should be intelligent enough to govern its transmission rate whenever 2 or more stations are gesturing at the same time. This test was repeated on the Ethernet LAN, and yielded similar results.

5.4 Video display

A final performance test was conducted in order to measure the processor overhead required for displaying different types of gesture pointers. This test consisted of drawing and erasing a 24x36 pixel bitmap or a 5 sided filled arrow polygon, of roughly the same area, 2000 times. We felt that the overhead of a *bitBlit* call might be larger than the overhead of a *drawPolygon* call. The test was run on four different CPUs (see Figure 5). For all CPUs, the drawing of the polygon was 4 to 5 times faster than the bitmap. The slowest CPU (Model 55) required 14 milliseconds for the bitmap and 3.8 milliseconds for the polygon, the fastest CPU (Gateway 486/33) required 4.1 milliseconds for the bitmap and .89 milliseconds for the polygon. As polygons are much faster to draw, gesturing programs should use this technique when running on slower processors. We acknowledge that these results are highly dependent on the video display hardware, but the test represents the current state of PC technology.

5.5 Summary

The above tests indicated that unreliable datagram communications are appropriate for gesturing and that a definite limit exists for transmitting and receiving gestures. This limit is determined by processor and network speed. To bet-
understand the processor limits, the following equation was derived from the test data:

\[
\rho_t = \beta((n-1)\gamma) + \alpha(\gamma) \leq 100% \\
\text{where} \\
\beta = \text{Msg Receive Time + Gesture Redraw Time} \\
\alpha = \text{Msg Send Overhead + Msg Send Time + Application Overhead} \\
\gamma = \text{Gesture rate in msgs per second} \\
n = \text{Number of users gesturing}
\]

Table 3 shows equation results for maximum gesture rates of bitmap and polygon cursors. If a rate of 10 messages per second is required for smooth gesturing, then low-end 386sx/16 systems could handle 3 concurrent gesturing stations and high-end 486/25 systems could handle 10 stations (using bitmap gestures). These calculations assume that there are no background tasks active. If large groups are to be supported on PC-based systems, gesturing needs to be viewed as a separate operation from drawing and other schemes such as “point and jitter” need to be explored. It is not required that all stations’ cursors be displayed at all times, but based on previous research and our own experience, the richness of the interaction is significantly reduced. Whether this becomes an impediment to successful group interaction is an empirical question.

6. Conclusions and Future Directions

In this paper we have addressed some of the practical considerations for gesturing within Group Support Systems applications. We have outlined a framework for implementing gesturing that spans low to high network bandwidth and processing power. The framework also addresses issues relevant to group size and interaction style.

We argue that the appearance of the gesture cursor should vary based on group size, user activity, and screen size. For small groups the cursor should be large enough to find and have some sort of owner identification (name, initials, etc.). For large groups (6+ and/or small screens (14” and smaller), cursors should be made smaller (16x16) and inactive cursors should decay or disappear. Ideally, the cursor shape will provide information about the current actions of the user (drawing, pointing, or requesting the floor). Finally, cursor update modes can be varied to accommodate system limitations. Full motion gesturing should be used whenever possible, with limited motion or point & quiver techniques reserved for slower networks.

During performance tests on PC networks we discovered that there is a large penalty for operating in the Windows GUI environment when transmitting messages. We also determined that the Ethernet or CSMA/CD protocol to be somewhat superior in small groups than the Token-Ring protocol using full motion gesturing; either provides more than enough bandwidth. As one might expect, the faster processors were able to transmit and receive more gesture messages per second. More importantly, slower CPUs will spend most of their time processing incoming gesture messages and will not be able to transmit messages of their own. Therefore, if equal participation is required, one must impose an adaptable governing mechanism that limits the transmission rates based on the number of stations participating or else limit the communication via the use of point and jitter and some smoothing mechanisms.

One might argue that all these problems can be solved by using high-performance workstations. However, for groupware to become commonly used in commercial environments, problems of this sort need to be solved. Further, when groupware applications are distributed geographically relying on low-speed networks, processor problems will be replaced with transmission latency problems. Perhaps the solutions we suggest to address slow processors can be applied to slow networks as well.

References


